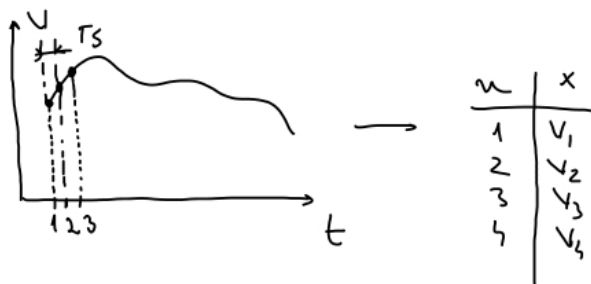


Filtru digital:



$f_s = \frac{1}{T_s}$ - frecvența de esantionare („sampling frequency“).

Criteriul Nyquist :

$f_s \geq 2 f_{max}$

IN
 $x(t) = A \cos(\omega t + \phi)$
 după esantionare:
 $x(n) = A \cos(\omega n T_s + \phi), \quad n = 0, 1, 2, \dots$

Funcția de transfer:

IN: $x(t) = \cos \omega t$
 \downarrow
 $x(n) = \cos(\omega n T_s)$

Vrem să determinăm ecuația diferențială a filtrului care realizează operația:

$y(n) = x(n) + x(n-1)$

$y(n) = \cos(\omega n T_s) + \cos[\omega(n-1) T_s] =$
 $= \cos(\omega n T_s) + \cos(\omega n T_s) \cos(\omega T_s) + \sin(\omega n T_s) \sin(\omega T_s)$

$y(n) = [1 + \cos(\omega T_s)] \cos(\omega n T_s) + \sin(\omega n T_s) \sin(\omega T_s)$

Vrem $y(\omega) = |G(\omega)| \cos[\omega n T_s + \theta(\omega)]$

$G(\omega)$ - câștigul („gain“)
 $\theta(\omega)$ - defazajul

$$y(n) = |G(\omega)| [\cos(\omega n T_s) \cos\theta(\omega) - \sin(\omega n T_s) \sin\theta(\omega)] =$$

$$= [|G(\omega)| \cos\theta(\omega)] \cos(\omega n T_s) - [|G(\omega)| \sin\theta(\omega)] \sin(\omega n T_s)$$

$$|G(\omega)| \cos\theta(\omega) = 1 + \cos(\omega T_s)$$

$$- |G(\omega)| \sin\theta(\omega) = \sin(\omega T_s)$$

$$- \frac{\cos\theta(\omega)}{\sin\theta(\omega)} = \frac{1 + \cos(\omega T_s)}{\sin(\omega T_s)}$$

$$- \operatorname{ctg}\theta(\omega) = \frac{1 + \cos(\omega T_s)}{\sin(\omega T_s)}$$

$$\left[\operatorname{ctg} \frac{x}{2} = \frac{1 + \cos x}{\sin x} \right] \Rightarrow$$

$$\Rightarrow \operatorname{ctg}(-\theta(\omega)) = \operatorname{ctg}\left(\frac{\omega T_s}{2}\right)$$

$$\theta(\omega) = -\frac{\omega T_s}{2}$$

$$- |G(\omega)| \sin\left(-\frac{\omega T_s}{2}\right) = \sin(\omega T_s)$$

$$|G(\omega)| \sin\left(\frac{\omega T_s}{2}\right) = 2 \sin\left(\frac{\omega T_s}{2}\right) \cos\left(\frac{\omega T_s}{2}\right)$$

$$|G(\omega)| = 2 \left| \cos\frac{\omega T_s}{2} \right|$$

$$\omega = 2\pi f; \quad T_s = \frac{1}{f_s}$$

$$|G(f)| = 2 \left| \cos\left(\pi \cdot \frac{f}{f_s}\right) \right| \quad f_s = 2 f_{\max}$$

$$\theta(f) = -\pi \cdot \frac{f}{f_s}$$

$$y(n) = x(n) + x(n-1) \rightarrow \text{LPF}$$

Alternativă (mai generală)

$$x(n) = A e^{j(\omega n T_s + \phi)}$$

$$x(n-1) = A e^{j(\omega(n-1)T_s + \phi)}$$

$$y(n) = x(n) + x(n-1) = A e^{j(\omega n T_s + \phi)} + A e^{j(\omega(n-1)T_s + \phi)}$$

$$y(n) = A e^{j\omega n T_s} (1 + e^{-j\omega T_s}) e^{j\phi}$$

$$\uparrow 1 + e^{-j\omega T_s} = e^{-j\frac{\omega T_s}{2}} \left(e^{j\frac{\omega T_s}{2}} + e^{-j\frac{\omega T_s}{2}} \right) =$$

$$= 2 e^{-j\frac{\omega T_s}{2}} \cos \frac{\omega T_s}{2}$$

$$y(n) = 2A \cos \frac{\omega T_s}{2} e^{j\left[\omega n T_s + \left(\phi - \frac{\omega T_s}{2}\right)\right]}$$

Forma generală a lui $y(n)$

$$y(n) = A \cdot G(\omega) e^{j[\omega n T_s + (\phi + \theta(\omega))]}$$

$$|G(\omega)| = 2 \left| \cos \frac{\omega T_s}{2} \right|$$

$$\theta(\omega) = -\frac{\omega T_s}{2}$$

$$y(n) = \underbrace{[G(\omega) e^{j\theta(\omega)}]}_{H(e^{j\omega T_s})} \underbrace{A \cdot e^{j(\omega n T_s + \phi)}}_{x(n)}$$

H-funcția de transfer

$$H(e^{j\omega T_s}) = G(\omega) e^{j\theta(\omega)}$$

Ecuația diferențială:

$$y(n) = b_0 x(n) + b_1 x(n-1) + b_2 x(n-2) + \dots + b_M x(n-M) - a_1 y(n-1) - a_2 y(n-2) - \dots - a_N y(n-N)$$

a_j, b_i - coeficienți de ponderare

$$y(n) = \sum_{i=0}^M b_i x(n-i) - \sum_{j=1}^N a_j y(n-j)$$

Filtre liniare invariante în timp

- reale: a_j, b_i - reali

- complexe: a_j, b_i - complecși.

- cauzale

- non-cauzale

Transformata z^u

- transformata Laplace discretă
- spațiul $z \rightarrow$ spațiul s discret.

$$x(n) = A e^{j(\omega n T_s + \phi)}$$

$$x(n-1) = A e^{j(\omega(n-1)T_s + \phi)} = A e^{j(\omega n T_s + \phi)} \cdot e^{-j\omega T_s} = x(n) e^{-j\omega T_s}$$

$$x(n-2) = A e^{j(\omega(n-2)T_s + \phi)} = x(n) e^{-2j\omega T_s}$$

$$\vdots$$
$$x(n-k) = x(n) e^{-j \cdot k \omega T_s}$$

$$z = e^{j\omega T_s}$$

$$x(n-k) = x(n) z^{-k}$$

$$X(z) = \sum_{n=0}^{\infty} x(n) z^{-n}$$

$$y(n) = x(n) + x(n-1)$$

Transf. z :

$$Y(z) = X(z) + X(z) z^{-1} = X(z) (1 + z^{-1})$$

Proprietățile transformatei z :

$$X(z) = Z(x)$$

$$\begin{aligned} 1) \quad Z(\alpha \cdot x_1(n) + \beta \cdot x_2(n)) &= \alpha Z(x_1(n)) + \beta Z(x_2(n)) = \\ &= \alpha X_1(z) + \beta X_2(z) \end{aligned}$$

$$2) \quad Z(x(n-M)) = z^{-M} \cdot Z(x(n)) = z^{-M} \cdot X(z)$$

ex: $y(n) = x(n) + x(n-1)$

transf. z

$$\begin{aligned} Z(y(n)) &= Z(x(n) + x(n-1)) = Z(x(n)) + Z(x(n-1)) = \\ &= Z(x(n)) + z^{-1} \cdot Z(x(n)) = (1 + z^{-1}) Z(x(n)) \end{aligned}$$

$$Y(z) = (1 + z^{-1}) X(z)$$

$$H(z) = \frac{Y(z)}{X(z)} = 1 + z^{-1} = 1 + e^{-j\omega T_s} = 2 \cos \frac{\omega T_s}{2} \cdot e^{-j \frac{\omega T_s}{2}}$$

În general:

$$\begin{aligned} y(n) &= b_0 x(n) + b_1 x(n-1) + \dots + b_M x(n-M) - \\ &- a_1 y(n-1) - a_2 y(n-2) - \dots - a_N y(n-N) \end{aligned}$$

$$\begin{aligned} Y(z) &= X(z) (b_0 + b_1 z^{-1} + \dots + b_M z^{-M}) - \\ &- Y(z) (a_1 z^{-1} + a_2 z^{-2} + \dots + a_N z^{-N}) \end{aligned}$$

$$Y(z) (1 + a_1 z^{-1} + \dots + a_N z^{-N}) = X(z) (b_0 + b_1 z^{-1} + \dots + b_M z^{-M})$$

$$\frac{Y(z)}{X(z)} = H(z) = \frac{b_0 + b_1 z^{-1} + \dots + b_M z^{-M}}{1 + a_1 z^{-1} + \dots + a_N z^{-N}}$$

Filtre în serie $H(z) = H_1(z) \cdot H_2(z)$

în paralel $H(z) = H_1(z) + H_2(z)$

$$|H(z)| = G(\omega)$$

$$\theta(\omega)$$

p - poli
 z - zerouri

$$H(z) = b_0 \cdot \frac{1 + \frac{b_1}{b_0} z^{-1} + \dots + \frac{b_M}{b_0} z^{-M}}{1 + a_1 z^{-1} + \dots + a_N z^{-N}}$$

not. $b_0 = g$

$$\frac{b_i}{b_0} = \beta_i$$

$$H(z) = g \cdot \frac{1 + \beta_1 z^{-1} + \dots + \beta_M z^{-M}}{1 + a_1 z^{-1} + \dots + a_N z^{-N}} =$$

$$= g \cdot \frac{z^{-M}}{z^{-N}} \cdot \frac{z^M + \beta_1 z^{M-1} + \dots + \beta_M}{z^N + a_1 z^{N-1} + \dots + a_N}$$

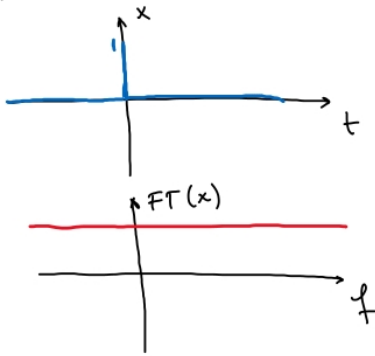
$$H(z) = g \cdot \frac{z^{-M}}{z^{-N}} \cdot \frac{(z - z_1)(z - z_2) \dots (z - z_M)}{(z - p_1)(z - p_2) \dots (z - p_N)}$$

p - poli
 z - zerouri

$$G(\omega) = |H(z)| = |g| \cdot \frac{|e^{j\omega T_s} - z_1| |e^{j\omega T_s} - z_2| \dots |e^{j\omega T_s} - z_M|}{|e^{j\omega T_s} - p_1| \dots |e^{j\omega T_s} - p_N|}$$

$$\theta(\omega) = (N-M)\omega T_s + \angle(e^{j\omega T_s} - z_1) + \dots + \angle(e^{j\omega T_s} - z_M) - \angle(e^{j\omega T_s} - p_1) - \dots - \angle(e^{j\omega T_s} - p_N)$$

Răspunsul la impuls unitar:



Ex: $y(n) = x(n) + x(n-1]$



$h(n)$ → răspunsul filterului la impuls unitar

în:

$$x(0) = 1$$

$$x(1) = 0$$

$$x(2) = 0$$

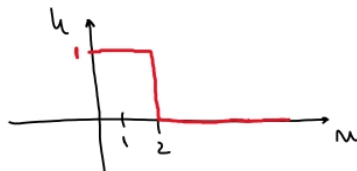
⋮

$$x(j) = 0$$

$$h(0) = x(0) + x(-1) = 1$$

$$h(1) = x(1) + x(0) = 0 + 1 = 1$$

$$h(2) = x(2) + x(1) = 0 + 0 = 0$$



filteru stabil → $h(n) \rightarrow 0, n \rightarrow \infty$

Probleme cu filtre digitale:

$H(z) \rightarrow G(\omega), \theta(\omega)$, tipul filtrului, ordinea filtrului

(P1.) $y(n) = x(n) + x(n-1)$

- transformata z^{-1} .

$$Z(y(n)) = Z(x(n) + x(n-1))$$

$$Y(z) = X(z) + z^{-1}X(z) = (1 + z^{-1})X(z)$$

$$H(z) = \frac{Y(z)}{X(z)} = 1 + z^{-1}$$

$$H(z) = z^{-1} \cdot (z + 1)$$

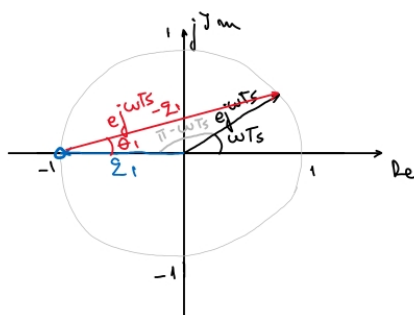
$z^{-1} \Rightarrow$ filtrul are ordinul
un zero
nici un pol

$$z + 1 = 0 \Rightarrow z = -1 = z_1$$

$$G(\omega) = |H(z)| = |z^{-1}(z+1)| = \underbrace{|z^{-1}|}_{1} |z+1|$$

$$z = e^{j\omega T_s}$$

Metoda grafică



$$c = |e^{j\omega T_s} - z_1|$$

$$a = |z_1| = 1$$

$$b = |e^{j\omega T_s}| = 1$$

Triunghi Pitagora generalizată

$$c^2 = a^2 + b^2 - 2ab \cos \alpha$$

$$\begin{aligned} c^2 &= a^2 + b^2 - 2ab \cos(\pi - \omega T_s) = \\ &= a^2 + b^2 - 2ab (\cos \pi \cos \omega T_s + \\ &\quad + \sin \pi \sin \omega T_s) = \\ &= a^2 + b^2 + 2ab \cos \omega T_s \end{aligned}$$

$$c = \sqrt{a^2 + b^2 + 2ab \cos \omega T_s}$$

$$\begin{aligned} |e^{j\omega T_s} - z_1| &= \sqrt{2 + 2 \cos \omega T_s} = \\ &= \sqrt{2(1 + \cos \omega T_s)} = \sqrt{4 \cos^2 \frac{\omega T_s}{2}} \end{aligned}$$

$$G(\omega) = |H(z)| = \left| \sqrt{4 \cos^2 \frac{\omega T_s}{2}} \right| = \left| \pm 2 \cos \frac{\omega T_s}{2} \right| = 2 \cos \frac{\omega T_s}{2}$$

$$H(z) = z^{-1} \cdot (z + 1)$$

$$\downarrow \quad \downarrow$$

$$\theta_0 \quad \theta_1$$

$$\theta(\omega) = \theta_0 + \theta_1$$

$$z^{-1} = e^{-j\omega T_s} = e^{j\theta_0}$$

$$\theta_0 = -\omega T_s$$

$$2\theta_1 + \pi - \omega T_s = \pi$$

$$2\theta_1 = \omega T_s$$

$$\theta_1 = \frac{\omega T_s}{2}$$

$$\theta(\omega) = -\omega T_s + \frac{\omega T_s}{2} = -\frac{\omega T_s}{2}$$

P2.

$$y(n) = x(n) + x(n-1] + y(n-1)$$

- transf. a z⁴.

$$Y(z) = X(z) + z^{-1}X(z) + z^{-1}Y(z)$$

$$Y(z)(1 - z^{-1}) = X(z)(1 + z^{-1})$$

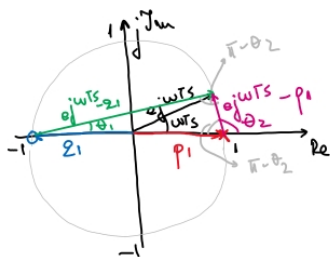
$$H(z) = \frac{Y(z)}{X(z)} = \frac{1 + z^{-1}}{1 - z^{-1}}$$

$$H(z) = \frac{z^{-1}(z + 1)}{z^{-1}(z - 1)}$$

$$H(z) = \frac{z + 1}{z - 1}$$

- ord. 1
- un zero → z + 1 = 0 ⇒ z = -1 = z₁
- un pol → z - 1 = 0 ⇒ z = 1 = p₁

$$H(z) = \frac{z - z_1}{z - p_1} \Rightarrow G(\omega) = |H(z)| = \frac{|e^{j\omega T_s} - z_1|}{|e^{j\omega T_s} - p_1|}$$



$$|e^{j\omega T_s} - z_1| = 2 \left| \cos \frac{\omega T_s}{2} \right|$$

$$\theta_1 = \frac{\omega T_s}{2}$$

$$c^2 = a^2 + b^2 - 2ab \cos \omega T_s$$

$$c = \sqrt{1 + 1 - 2 \cos \omega T_s} = \sqrt{2(1 - \cos \omega T_s)} = \sqrt{4 \sin^2 \frac{\omega T_s}{2}} = 2 \sin \frac{\omega T_s}{2}$$

$$|e^{j\omega T_s} - p_1| = 2 \left| \sin \frac{\omega T_s}{2} \right|$$

$$G(\omega) = \frac{2 \left| \cos \frac{\omega T_s}{2} \right|}{2 \left| \sin \frac{\omega T_s}{2} \right|} = \left| \cotg \frac{\omega T_s}{2} \right| = \left| \cotg \pi \cdot \frac{f}{f_0} \right|$$

$$\vartheta(\omega) = \theta_1 - \theta_2$$

$$\omega T_s + 2\pi - 2\theta_2 = \pi$$

$$-2\theta_2 = -\pi - \omega T_s$$

$$\theta_2 = \frac{\pi}{2} + \frac{\omega T_s}{2}$$

$$\vartheta(\omega) = \frac{\omega T_s}{2} - \frac{\pi}{2} - \frac{\omega T_s}{2}$$

$$\vartheta(\omega) = -\frac{\pi}{2}$$

Temă: analiza și simularea filtrului digital:
 $y(n) = x(n-1] + x(n-2) + y(n-1)$.