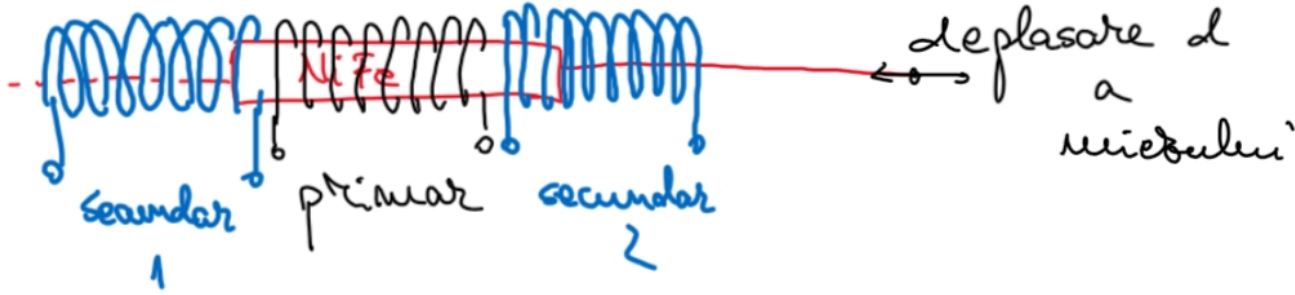


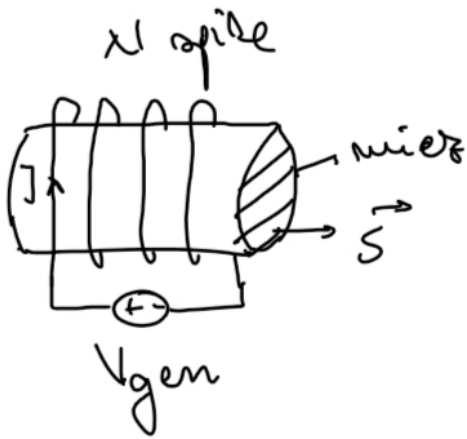
Transformatorul diferentia1 linear variabil:

LVDI - "Linear Variable Differential Transformer"



Deplasarea miezului duce la variatia factorului de cuplaj intre primar si cei doi secundari, (implicit o variatie a raportului de transformare).

Legea lui Faraday



tensiune electromotoare indusa

$$t.e.m. = -N \frac{d\phi}{dt}$$

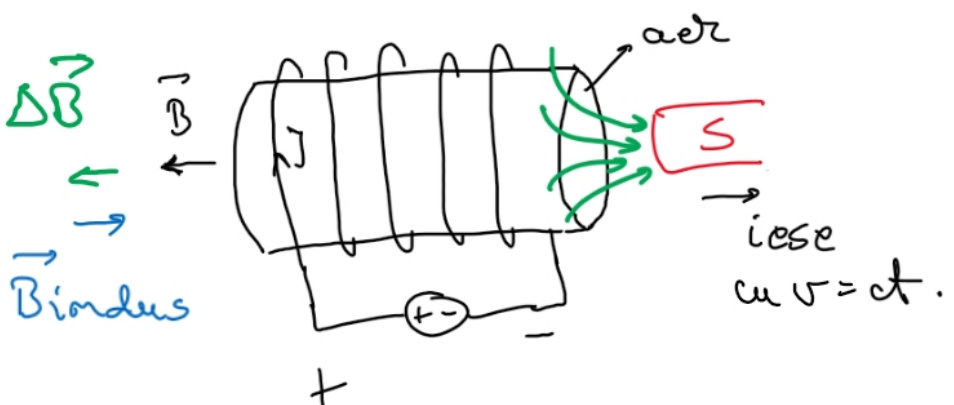
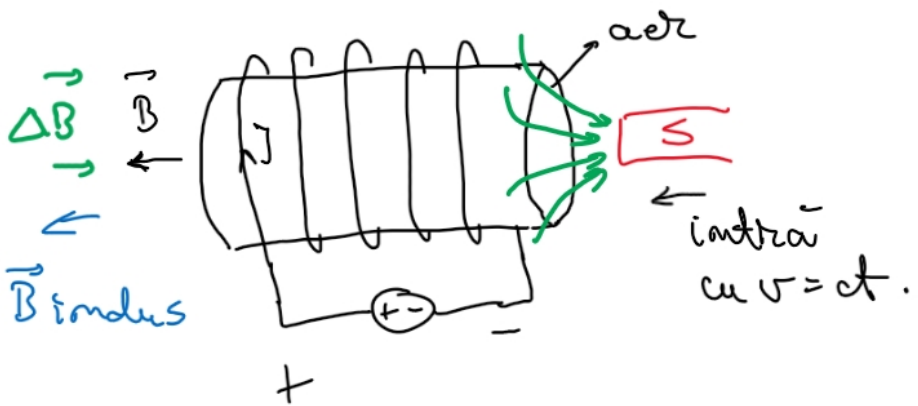
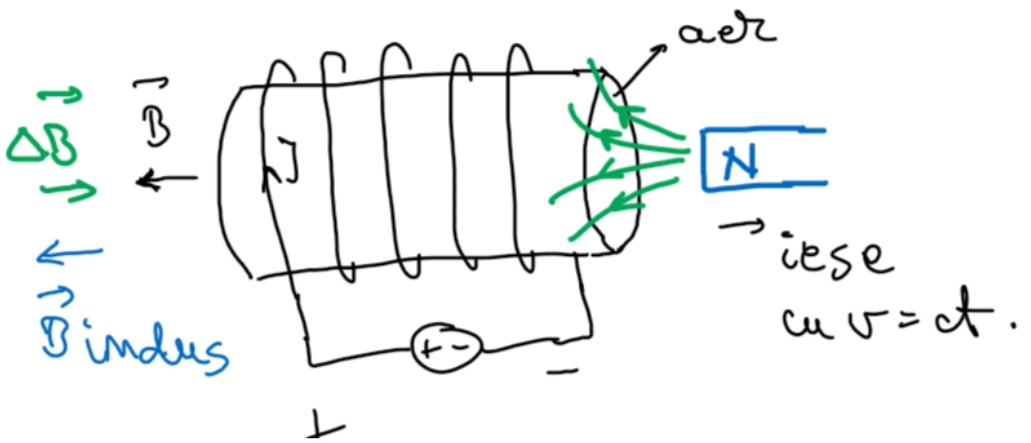
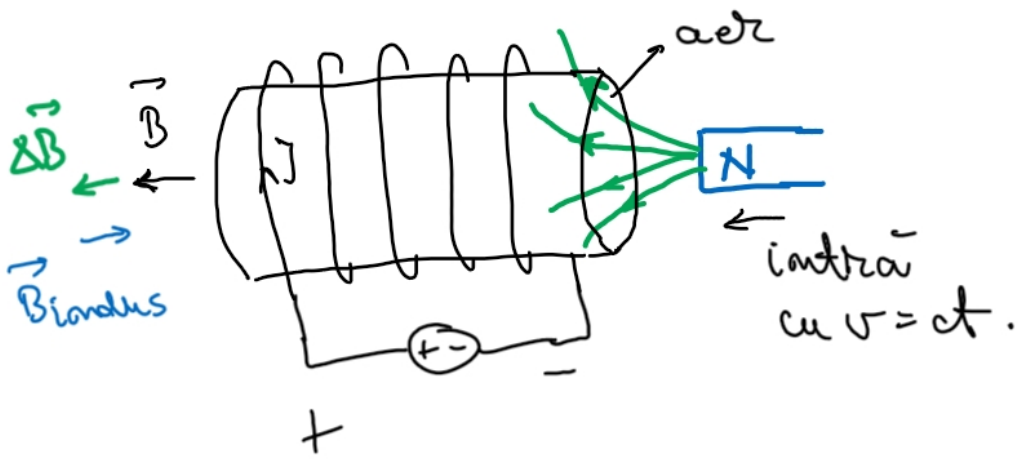
ϕ - fluxul magnetic (Wb)

t - timpul (s)

N - nr. de spire.

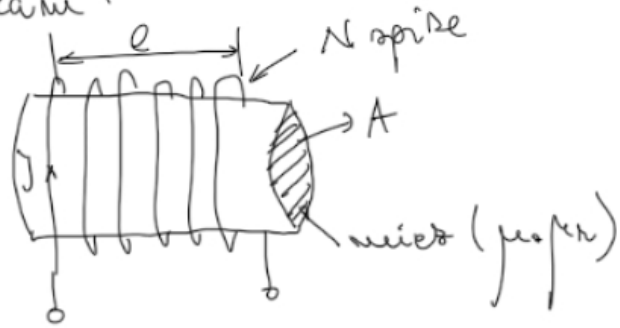
$-\frac{d\phi}{dt} \rightarrow$ legea lui Lenz $\rightarrow \phi = ct.$

.) exemple pt. legea lui Lenz

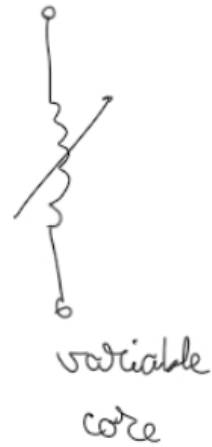
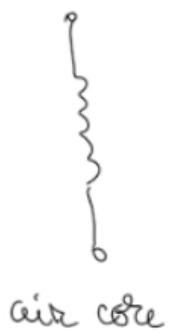


Inductanța (self-inductance):

Considerăm:



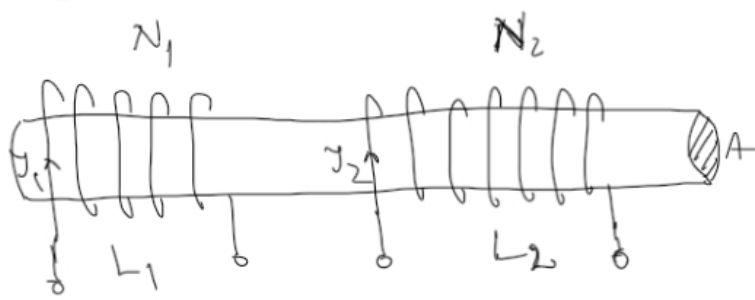
simboluri:



Legea lui Faraday: $V_L = -N \frac{d\phi}{dt}$ } $\Rightarrow V_L = -L \frac{di}{dt}$ → Faraday (Lenz)

$N\phi = Li$ $L = \frac{\mu_0 \mu_r N^2 A}{l}$ inductanța (H)

Inductanța mutuală ("mutual inductance")



$$M = \frac{\mu_0 \mu_r N_1 N_2 A}{l}$$

Dacă avem curent prin L_1 :

$$M_{12} = \frac{N_2 \phi_{12}}{I_1}$$

$$M_{21} = \frac{N_1 \phi_{21}}{I_2}$$

$$\text{Dacă } I_1 = I_2 \Rightarrow M_{12} = M_{21} = M$$

$$L_1 = \frac{\mu_0 \mu_r N_1^2 A}{l} \quad ; \quad L_2 = \frac{\mu_0 \mu_r N_2^2 A}{l}$$

$$M^2 = L_1 L_2$$

$M = \sqrt{L_1 L_2}$ pentru cuplaj perfect.

Factor de cuplaj k

$$M = k \sqrt{L_1 L_2} \quad [H]$$

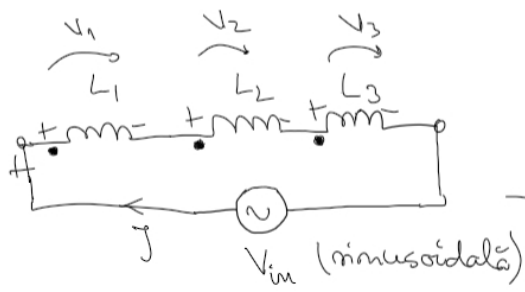
$$k = 0 - 1 \quad (0 - 100\%)$$

$k = 1$ - cuplaj perfect

$k > 0.5$ "tight coupling"

$k < 0.5$ "loose coupling"

Inductori în serie fără cuplaj:



Legea lui Ohm pt. inductori

$$V = L \cdot \frac{dI}{dt}$$

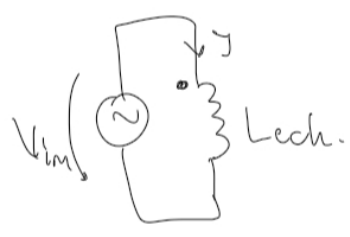
$$V_{im} = V_1 + V_2 + V_3$$

$$V_{im} = L_{ech} \cdot \frac{dI}{dt}$$

$$L_{ech} \cdot \frac{dI}{dt} = L_1 \cdot \frac{dI}{dt} + L_2 \cdot \frac{dI}{dt} + L_3 \cdot \frac{dI}{dt}$$

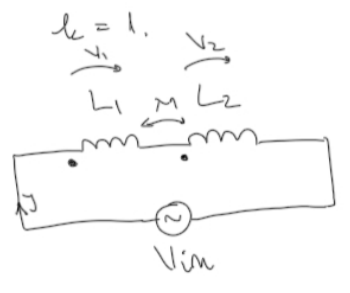
$$L_{ech} \cdot \frac{dI}{dt} = (L_1 + L_2 + L_3) \cdot \frac{dI}{dt}$$

$$L_{ech} = L_1 + L_2 + L_3$$

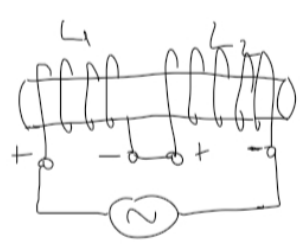


Inductori în serie cuplați:

cuplaj în față („aiding“)



$L_{ech} = ?$



$$V_{im} = V_1 + V_2$$

$$V_{im} = L_{ech} \cdot \frac{dI}{dt}$$

$$V_1 = L_1 \cdot \frac{dI}{dt} + M \cdot \frac{dI}{dt}$$

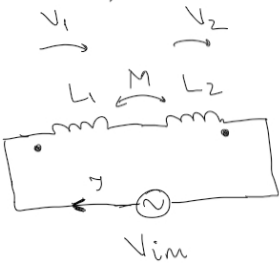
$$V_2 = L_2 \cdot \frac{dI}{dt} + M \cdot \frac{dI}{dt}$$

$$\Rightarrow L_{ech} \cdot \frac{dI}{dt} = L_1 \cdot \frac{dI}{dt} + M \cdot \frac{dI}{dt} + L_2 \cdot \frac{dI}{dt} + M \cdot \frac{dI}{dt}$$

$$L_{ech} \cdot \frac{dI}{dt} = (L_1 + L_2 + 2M) \cdot \frac{dI}{dt}$$

$$L_{ech} = L_1 + L_2 + 2M$$

Inductori cuplați în opoziție („opposing“)



$$V_{in} = V_1 + V_2$$

$$V_{in} = L_{ech} \frac{dI}{dt}$$

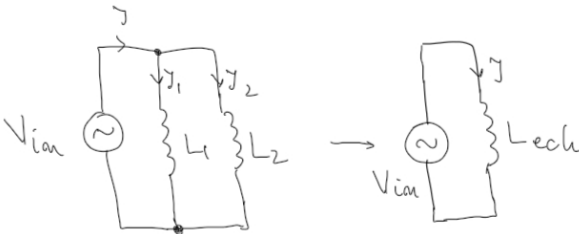
$$V_1 = L_1 \frac{dI}{dt} - M \frac{dI}{dt}$$

$$V_2 = L_2 \frac{dI}{dt} - M \frac{dI}{dt}$$

$$\Rightarrow L_{ech} \frac{dI}{dt} = (L_1 - M) \frac{dI}{dt} + (L_2 - M) \frac{dI}{dt}$$

$$L_{ech} = L_1 + L_2 - 2M$$

Inductori în paralel fără cuplaj:



$$V_{in} = L_{ech} \frac{dI}{dt}$$

$$I = I_1 + I_2$$

$$\frac{dI}{dt} = \frac{dI_1}{dt} + \frac{dI_2}{dt}$$

$$V_{in} = L_1 \frac{dI_1}{dt} = L_2 \frac{dI_2}{dt} = L_{ech} \frac{dI}{dt}$$

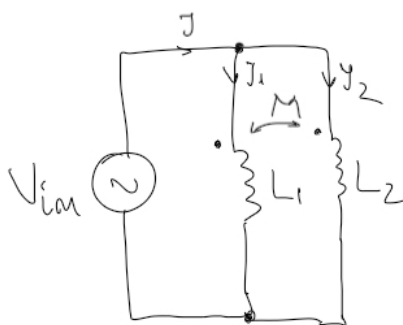
$$\frac{dI_1}{dt} = \frac{V_{in}}{L_1} \quad \frac{dI_2}{dt} = \frac{V_{in}}{L_2} \quad \frac{dI}{dt} = \frac{V_{in}}{L_{ech}}$$

$$\frac{V_{in}}{L_{ech}} = \frac{V_{in}}{L_1} + \frac{V_{in}}{L_2}$$

$$\frac{1}{L_{ech}} = \frac{1}{L_1} + \frac{1}{L_2}$$

$$L_{ech} = \frac{L_1 L_2}{L_1 + L_2}$$

Inductori în paralel cuplați în fașă



$$\frac{dJ}{dt} = \frac{dJ_1}{dt} + \frac{dJ_2}{dt}$$

$$V_{im} = L_{ech} \frac{dJ}{dt}$$

$$V_{im} = L_1 \frac{dJ_1}{dt} + M \frac{dJ_2}{dt}$$

$$V_{im} = L_2 \frac{dJ_2}{dt} + M \frac{dJ_1}{dt}$$

$$L_2 \frac{dJ_2}{dt} + M \frac{dJ_1}{dt} = L_1 \frac{dJ_1}{dt} + M \frac{dJ_2}{dt}$$

$$(L_2 - M) \frac{dJ_2}{dt} = (L_1 - M) \frac{dJ_1}{dt}$$

$$V_{im} = L_1 \frac{dJ_1}{dt} + M \frac{L_1 - M}{L_2 - M} \frac{dJ_1}{dt}$$

$$V_{im} = \frac{dJ_1}{dt} \left(L_1 + \frac{M(L_1 - M)}{L_2 - M} \right)$$

$$V_{im} = L_2 \frac{dJ_2}{dt} + M \left(\frac{L_2 - M}{L_1 - M} \right) \frac{dJ_2}{dt}$$

$$V_{im} = \frac{dJ_2}{dt} \left(L_2 + M \frac{L_2 - M}{L_1 - M} \right)$$

$$L_{\text{ech}} = L_1 + \frac{M(L_1 - M)}{L_2 - M} + L_2 + \frac{M(L_2 - M)}{L_1 - M} =$$

$$= \frac{L_1(L_2 - M) + M(L_1 - M)}{L_2 - M} + \frac{L_2(L_1 - M) + M(L_2 - M)}{L_1 - M} =$$

$$= \frac{(L_1 - M)[L_1(L_2 - M) + M(L_1 - M)] + (L_2 - M)[L_2(L_1 - M) + M(L_2 - M)]}{(L_1 - M)(L_2 - M)} =$$

$$= \frac{(L_1 - M)[L_1 L_2 - \cancel{L_1 M} + \cancel{L_1 M} - M^2] + (L_2 - M)[L_1 L_2 - \cancel{L_2 M} + \cancel{L_2 M} - M^2]}{(L_1 - M)(L_2 - M)} =$$

$$= \frac{(L_1 L_2 - M^2)(L_1 - M + L_2 - M)}{(L_1 - M)(L_2 - M)} = \frac{L_1^2 L_2 + L_2^2 L_1 - 2ML_1 L_2 - L_1 M^2 - L_2^2 M_2 + 2M^3}{(L_1 - M)(L_2 - M)}$$